

Calibration results

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Camera-system parameters:

cam0 (/cam00/image_raw):

type: <class 'aslām_cv.libaslām_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.17961615 0.06234032 0.01081533 0.00123196] +- [0.00364123 0.00908537 0.00060732 0.0002414]

projection: [1589.45252361 1569.62265838 769.37310456 476.5312425] +- [0.84998471 1.48698207 2.56973903
3.75448596]

reprojection error: [-0.000002, 0.000122] +- [0.303247, 0.315689]

Target configuration

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Type: aprilgrid

Tags:

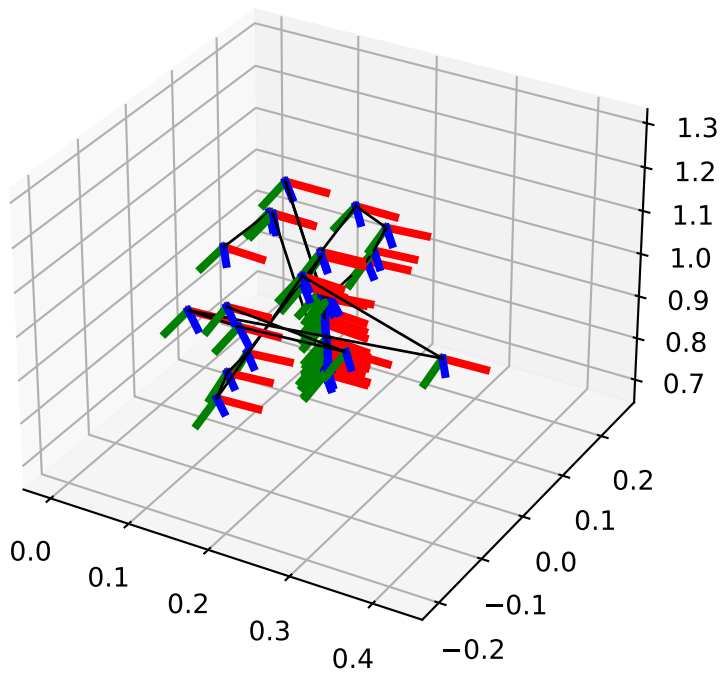
Rows: 6

Cols: 6

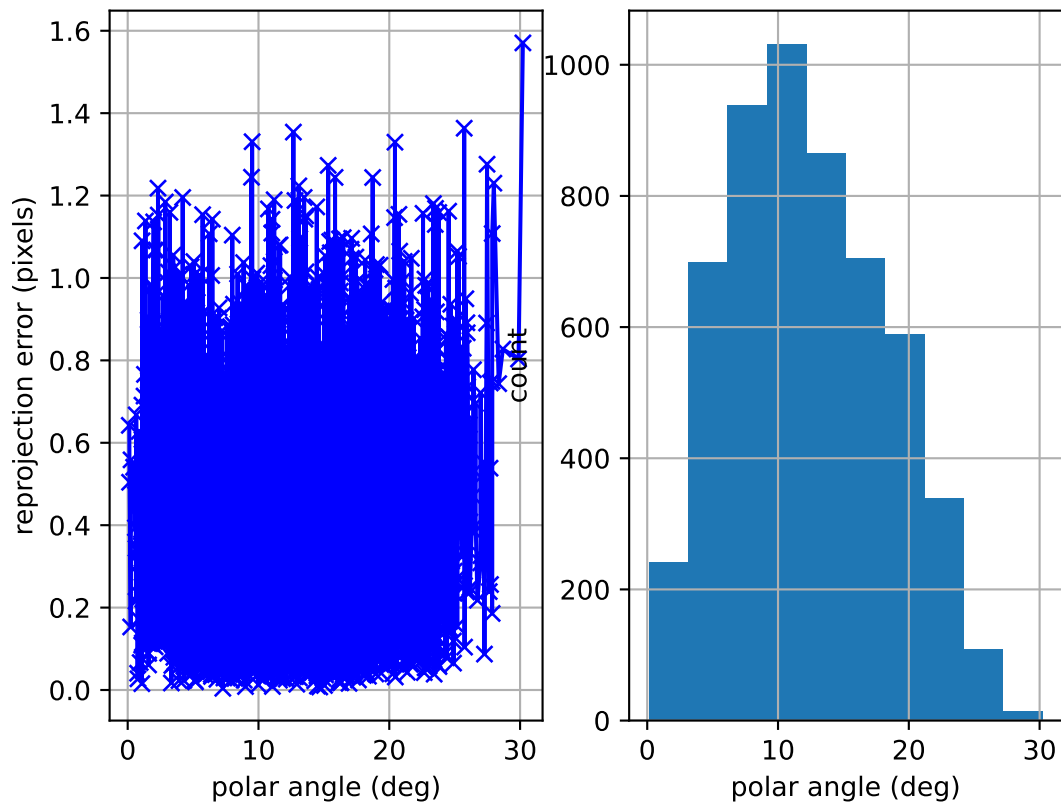
Size: 0.044 [m]

Spacing 0.013199999999999998 [m]

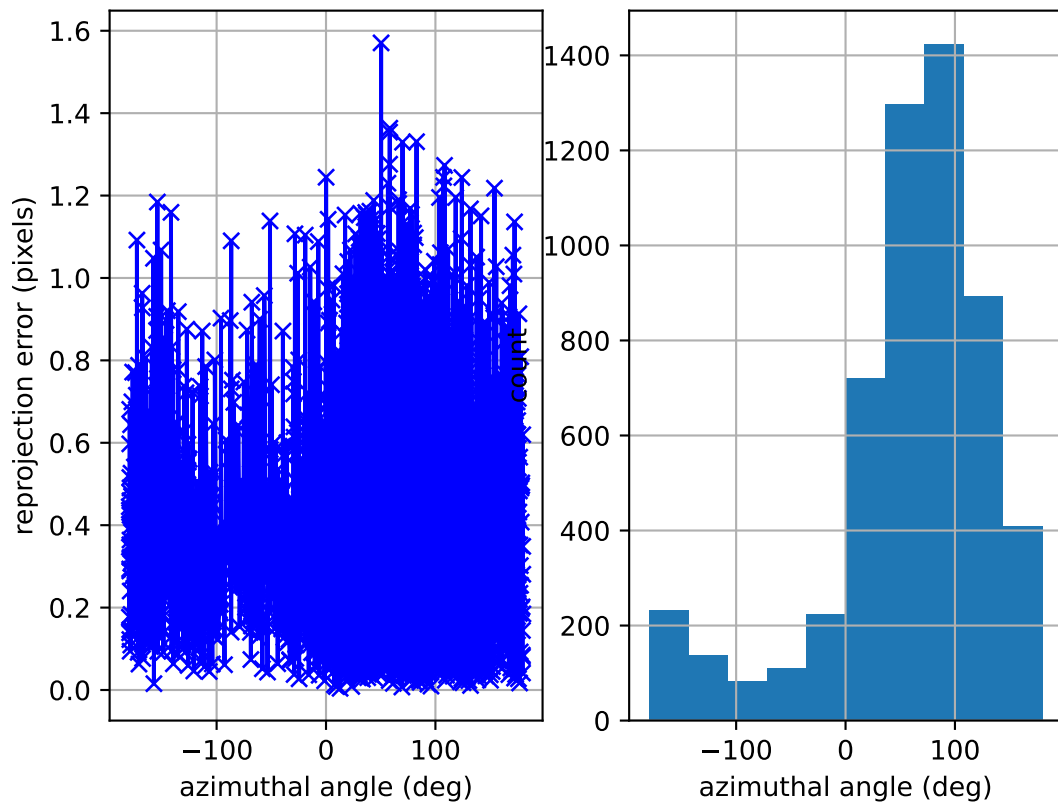
cam0: estimated poses



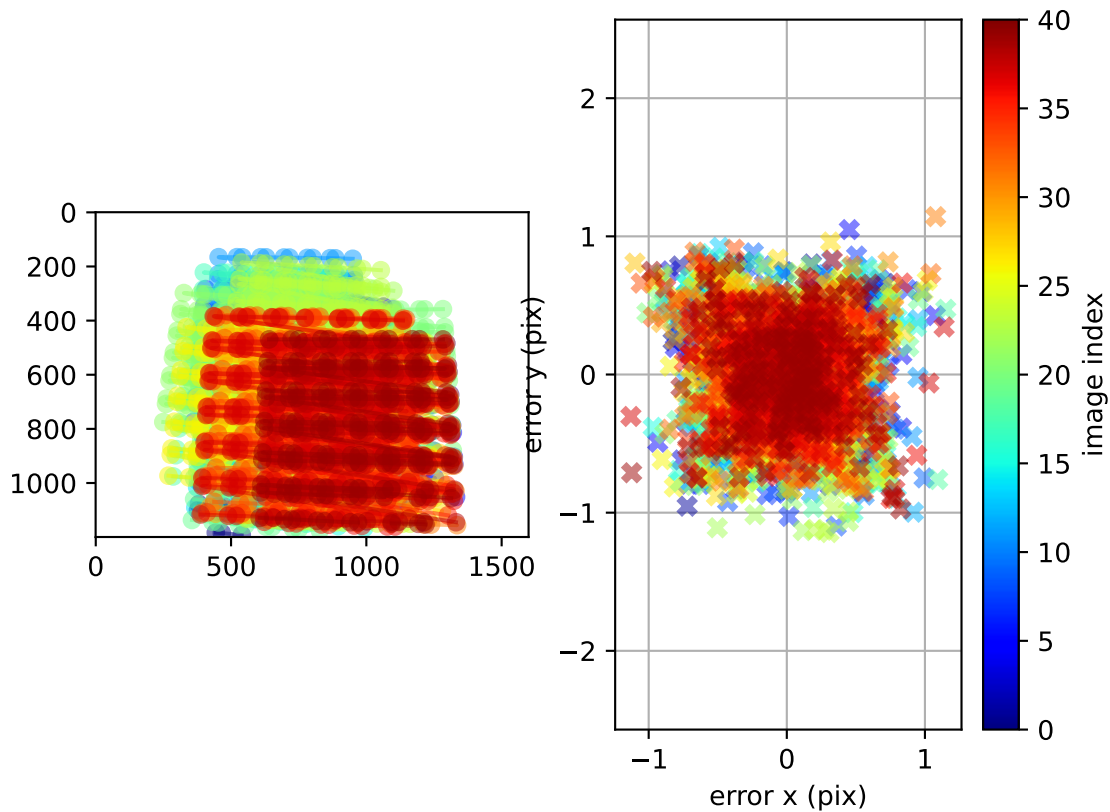
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

